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## IN THE CLAIMS

## I claim:

[Claim] 1.(currently amended) A robotic package unloading system for unloading [uniform as well as non-uniform and non-structured] bulk packages, comprising:

a container for holding [at least] more than one packages, selected from the group consisting of: uniformly shaped packages that have been stacked in a uniform pattern package, uniformly shaped packages that have been stacked in a random pattern, different shaped packages that have been stacked in a uniform pattern, and different shaped packages that have been stacked in a random pattern;

a robotic manipulator, wherein an end-of-arm tool is used to grip said package; [a takeaway conveyor for moving said package,]

conveying [means which is actively positioned to engage the package at one end and to be connected to said takeaway conveying at second end] system for moving said packages,

wherein said conveying system has at least two sections connected with a flexible joint, wherein the first section of said two sections is positioned where one of the packages is removed from

## the container.

wherein the second section of said two sections interfaces with a fixed takeaway conveyor, and wherein the second section of said two sections is allowed to articulate and maintain a physical interface between the first conveyor section and the fixed takeaway conveyor;

a[n image/] sensor to identify and locate said package in said container; and a computer to control and process said robotic manipulator,[ said articulating belt] said conveyor system, and said [image/] sensor.

[Claim] 2. (currently amended) The robotic package loading system as described in claim 1, wherein said conveying [means] system is [an articulating belt] a belt conveyor.

[Claim] 3. (currently amended) The robotic package unloading system as described in claim 1, wherein said conveying [means] system is a slide.

[Claim] 4. (currently amended) The robotic package unloading system as described in claim 1, further comprising:

a carriage for mounting said robotic manipulator and a section of said conveying system; a carriage lift frame along which the carriage can move up and down; and